

#### **ANS PHYSOR2022**

May 15-20, 2022, Pittsburgh, PA, USA

Christophe Demazière – Chalmers University of Technology <u>demaz@chalmers.se</u>



### Introduction

- Special emphasis in CORTEX on fuel assembly vibrations
- Neutron noise induced by fuel assembly vibrations often modelled by coarse mesh approaches
- Purpose of this work:

To investigate whether coarse mesh approaches can reproduce the global behavior of the neutron noise



## Introduction

- Plan of the presentation:
  - Modelling of fuel assembly vibrations
  - System considered and approximations used
  - Results:
    - Theoretical considerations
    - Heterogeneous systems
    - Homogenized systems
  - Conclusions





• Fuel assembly vibrations = displacement of the boundaries between "homogeneous" regions





• Illustration on a moving interface between two homogeneous regions:



➢ Static cross-section representation:

$$\boldsymbol{\Sigma}_{\scriptscriptstyle \boldsymbol{\alpha},\boldsymbol{0}}\left(\boldsymbol{x}\right) = \left[\boldsymbol{1} - \mathbf{H}\left(\boldsymbol{x} - \boldsymbol{b}_{\scriptscriptstyle \boldsymbol{0}}\right)\right]\boldsymbol{\Sigma}_{\scriptscriptstyle \boldsymbol{\alpha},\boldsymbol{I}} + \mathbf{H}\left(\boldsymbol{x} - \boldsymbol{b}_{\scriptscriptstyle \boldsymbol{0}}\right)\boldsymbol{\Sigma}_{\scriptscriptstyle \boldsymbol{\alpha},\boldsymbol{II}}$$

>Dynamic cross-section representation:

$$\delta \Sigma_{_{\alpha}}\left(x,t\right) = -\Delta \Sigma_{_{\alpha}} \mathrm{H}\left(x-b_{_{0}}\right) + \Delta \Sigma_{_{\alpha}} \mathrm{H}\left(x-b_{_{0}}-\varepsilon\left(t\right)\right)$$

with

$$\Delta \Sigma_{\alpha} = \Sigma_{\alpha, II} - \Sigma_{\alpha, I}$$



• Illustration on a moving interface between two homogeneous regions: For  $\varepsilon(t) = d \sin(\omega_0 t)$  and using the model of Rouchon and Sanchez<sup>\*</sup>, one obtains in the frequency domain at the fundamental frequency  $\omega_0$ :

$$\begin{split} \delta \Sigma_{\alpha} \left( x, \omega_{_{0}} \right) &= 2\iota \Delta \Sigma_{\alpha} \cos \left[ \omega_{_{0}} \tau \left( x \right) \right] \\ \text{with} \quad \tau \left( x \right) &= \frac{1}{\omega_{_{0}}} \operatorname{arcsin} \left( \frac{x - b_{_{0}}}{d} \right) \quad \text{and for} \quad x \in \left[ b_{_{0}} - d; b_{_{0}} + d \right] \end{split}$$

\*Rouchon A. and Sanchez R., "Analysis of vibration-induced neutron noise using one-dimension noise diffusion theory," Proc. Int. Congress on Advances in Nuclear Power Plants (ICAPP2015), Nice, France, May 3-5, 2015 (2015).



 After homogenization = displacement of only two boundaries between "homogeneous" regions





 After homogenization = displacement of only two boundaries between "homogeneous" regions





• Illustration on a moving interface between two homogeneous regions: Approximated treatment relying on the  $\varepsilon/d$  model of Pazsit\* giving at the fundamental frequency  $\omega_0$ :

$$\delta \Sigma_{_{\alpha}}\left(x,\omega_{_{0}}\right) = \mathcal{F}\left\{\varepsilon\left(t\right)\right\}_{_{\omega_{_{0}}}} \delta\left(x-b_{_{0}}\right) \Delta \Sigma_{_{\alpha}}$$

\*Jonsson A., Tran H.N., Dykin V. and Pázsit I., "Analytical investigation of the properties of neutron noise induced by vibrating absorber and control rods," Kerntechnik, 77 (5), pp. 371-380 (2012).



# System considered and approximations used



## System considered and approximations used

- I-D PWR model of 361.25 cm
- 15 fuel assemblies, each containing 17 fuel pins
- Core surrounded by reflector
- Two-group diffusion theory
- Frequency domain
- Linear theory
- No thermal-hydraulic feedback
- Effect of the noise source estimated numerically using CORE SIM
- Fine mesh of 0.00125 cm used throughout the entire work



## Results



## **Results – theoretical considerations**

• In two-group theory, neutron noise given as:

$$\begin{bmatrix} \delta\phi_{1}\left(x,\omega\right) \\ \delta\phi_{2}\left(x,\omega\right) \end{bmatrix} = \begin{bmatrix} \int_{V} \left[ G_{1\rightarrow1}\left(x,x',\omega\right)S_{1}\left(x',\omega\right) + G_{2\rightarrow1}\left(x,x',\omega\right)S_{2}\left(x',\omega\right) \right] dx' \\ \int_{V} \left[ G_{1\rightarrow2}\left(x,x',\omega\right)S_{1}\left(x',\omega\right) + G_{2\rightarrow2}\left(x,x',\omega\right)S_{2}\left(x',\omega\right) \right] dx' \end{bmatrix}$$

with

$$\begin{bmatrix} S_1(x',\omega) \\ S_2(x',\omega) \end{bmatrix} = \Phi_r(x')\delta\Sigma_r(x',\omega) + \Phi_a(x')\begin{bmatrix} \delta\Sigma_{a,1}(x',\omega) \\ \delta\Sigma_{a,2}(x',\omega) \end{bmatrix} + \Phi_f(x',\omega)\begin{bmatrix} \delta\nu\Sigma_{f,1}(x',\omega) \\ \delta\nu\Sigma_{f,2}(x',\omega) \end{bmatrix}$$
  
> In the  $\varepsilon/d$  model, 2 noise sources  $S_1$  and  $S_2$  entirely defining the problem for each vibrating boundary



## **Results – theoretical considerations**

After spatial homogenization, problem only requiring 4 noise sources
 >4 conditions necessary



## **Results for heterogeneous systems**

• Normalization to the actual solution at the two locations of the introduced noise sources, for both the fast and the thermal group:



Very good agreement for the fast neutron noise



## **Results for heterogeneous systems**

• Normalization to the actual solution at the two locations of the introduced noise sources, for both the fast and the thermal group:



>Very good agreement for the thermal neutron noise



## **Results for heterogeneous systems**

- 4 noise sources sufficient to reproduce the actual neutron noise
- Same level of accuracy obtained when replacing 2 of the 4 necessary conditions by a normalization to the same reactivity effect, evaluated:
  - Either using the spatial dependence of the actual solution, e.g., for the thermal group:

$$\delta\rho_{_{2,\delta\phi}}\left(\omega\right) = \frac{1}{A_{_{0}}G_{_{0}}\left(\omega\right)} \int_{_{V}} \frac{1}{v_{_{2}}} \phi_{_{2,0}}^{_{+}}\left(x\right) \delta\phi_{_{2}}^{^{\mathrm{reconstructed}}}\left(x,\omega\right) dx = \frac{1}{A_{_{0}}G_{_{0}}\left(\omega\right)} \int_{_{V}} \frac{1}{v_{_{2}}} \phi_{_{2,0}}^{_{+}}\left(x\right) \delta\phi_{_{2}}^{^{\mathrm{reference}}}\left(x,\omega\right) dx$$

• Or using the perturbations of the cross-sections directly (preferable), e.g., for the thermal group:

$$\begin{split} \delta\rho_{2,\delta\Sigma}\left(\omega\right) &= \frac{1}{F_0} \int\limits_{V} \left\{ \delta\Sigma_r^{\text{reconstructed}}\left(x,\omega\right) \phi_{2,0}^+\left(x\right) \phi_{1,0}\left(x\right) - \delta\Sigma_{a,2}^{\text{reconstructed}}\left(x,\omega\right) \phi_{2,0}^+\left(x\right) \phi_{2,0}\left(x\right) \right\} dx \\ &= \frac{1}{F_0} \int\limits_{V} \left\{ \delta\Sigma_r^{\text{reference}}\left(x,\omega\right) \phi_{2,0}^+\left(x\right) \phi_{1,0}\left(x\right) - \delta\Sigma_{a,2}^{\text{reference}}\left(x,\omega\right) \phi_{2,0}^+\left(x\right) \phi_{2,0}\left(x\right) \right\} dx \end{split}$$

## **Results for homogenized systems**

• Normalization to the actual solution at the two locations of the introduced noise sources, for the fast/thermal groups, respectively:



Very good agreement for the fast neutron noise



## **Results for homogenized systems**

• Normalization to the actual solution at the two locations of the introduced noise sources, for the fast/thermal groups, respectively:



>Very good agreement for the thermal neutron noise



## Conclusions



## Conclusions

- Neutron noise successfully reproduced at the global scales after assembly homogenization, using only 4 noise sources and using the  $\varepsilon/d$  model
- Truly remarkable results

(but noise source weights to be estimated)





#### **ANS PHYSOR2022**

May 15-20, 2022, Pittsburgh, PA, USA

Christophe Demazière – Chalmers University of Technology <u>demaz@chalmers.se</u>

