

CORTEX

Core monitoring techniques and
experimental validation and demonstration

Analysis of the experimental data

Validation workshop, 12-13.03.20

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Outline: Quantities of Interest

- Following the validation meetings:
 - QoI are CPSD relative power & phase
- Using exp. 20 on CROCUS reactor at ± 1.5 mm/1Hz
 - 30 min measurement
 - Dwell time 0.004 s
 - $\sim 4.5 \cdot 10^5$ samples
- Post-processing
 - Signal Coherence (checking data validity)
 - Power density estimate
 - Uncertainty estimates



Outline: analysis steps

- Detrending: removal of low frequency shifts (e.g. reactor power change) and normalization by removing moving average

- Requirement: mean=0

Impacted by detrending window size

- PSD estimates using Welch averaging

Impacted by both detrending and Welch sample window size

- Coherence determination

Are signals biased or not?

- Determination of PSD peak frequency and area

- Effects of Welch averaging (windowing) on peak area

- Uncertainty estimates using bootstrapping

- Using power ratios



Experimental data

For both 1st campaigns, the neutron detection time series arise from:

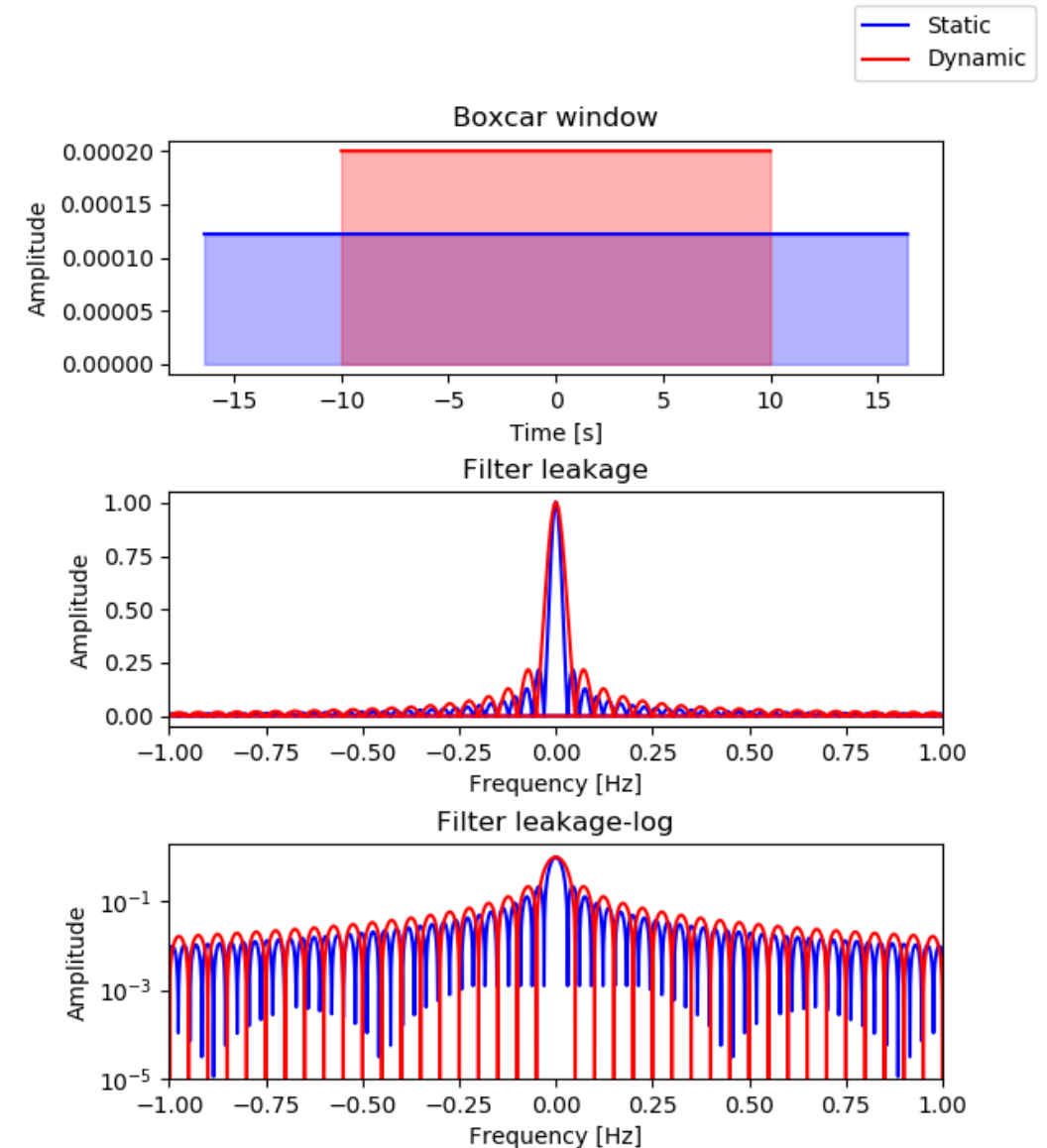
- Measuring various reactions rates: ^{235}U , ^3He , ^{10}B
- Various detectors' types
 - ^{235}U fission chambers
 - $^3\text{He}/\text{BF}_3$ proportional counters
 - ^{10}B -coated compensated ionisation chambers
- Various electronics' types
 - Pulse mode, i.e. counting detection events
 - Current mode, i.e. measuring energy deposits
- One acquisition system as of now: ISTec SIGMA
 - Pulses are converted in current using Robotron devices

Please refer to deliverable D2.1!



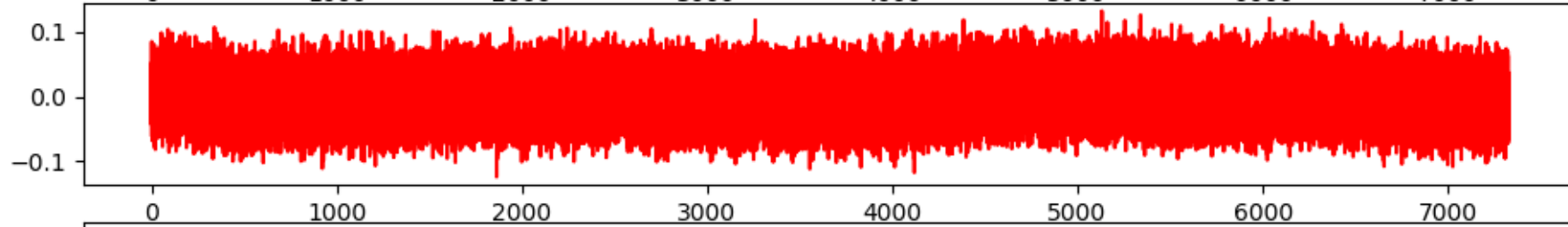
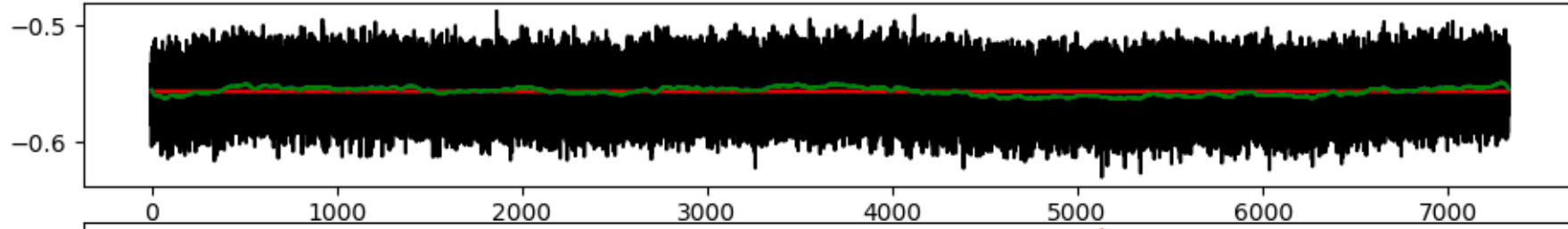
Detrending

- Motivation:
 - Need of data with 0 mean for analysis
 - Removal of low frequency data shifts, not induced by the oscillator (e.g. reactor power change)
- Methods:
 - Mean removal
 - Moving average removal, static or dynamic
- Effects of averaging window size:
 - Static: use the window size used for PSD estimate
 - Dynamic: use the window size of 2x the wavelength of estimated base frequency by the initial PSD estimate.

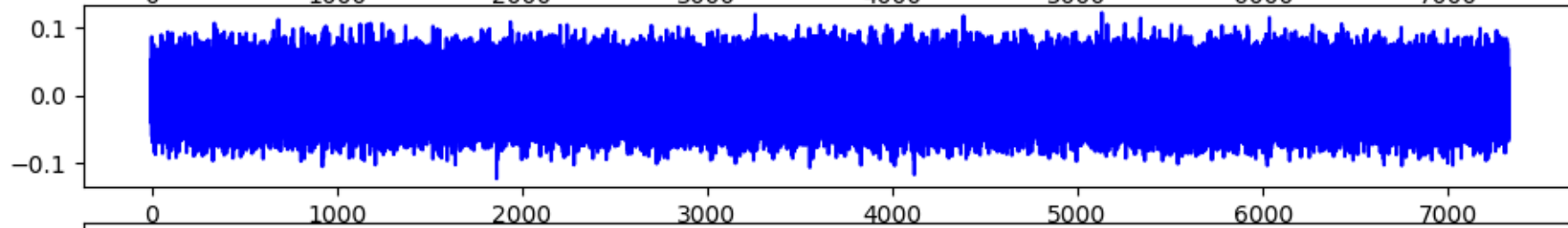


Comparison of Data detrending

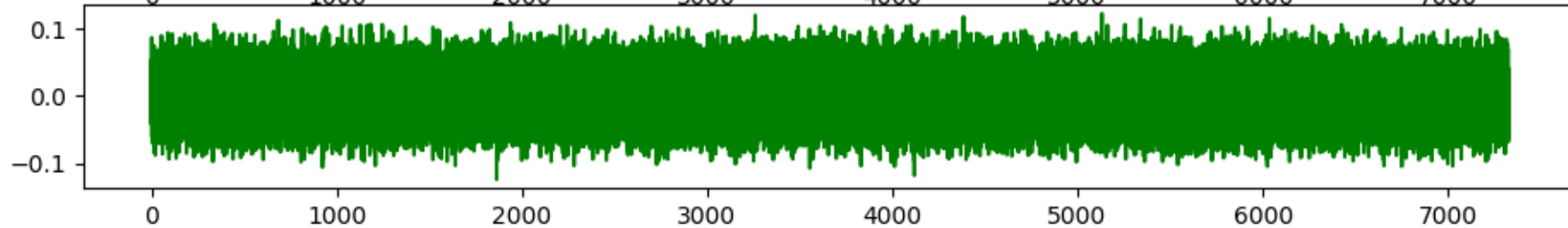
- Original data
- Mean detrend
- Static detrend
- Dynamic detrend ← *Our selection*



Observable low frequency trend



At this stage, series seem fine



time[s]



PSD estimates using Welch

- Averaging periodograms ($|FFT|^2$) of several signal sections (W window size samples), here without overlapping
- Lowering the spectral resolution compared to periodogram

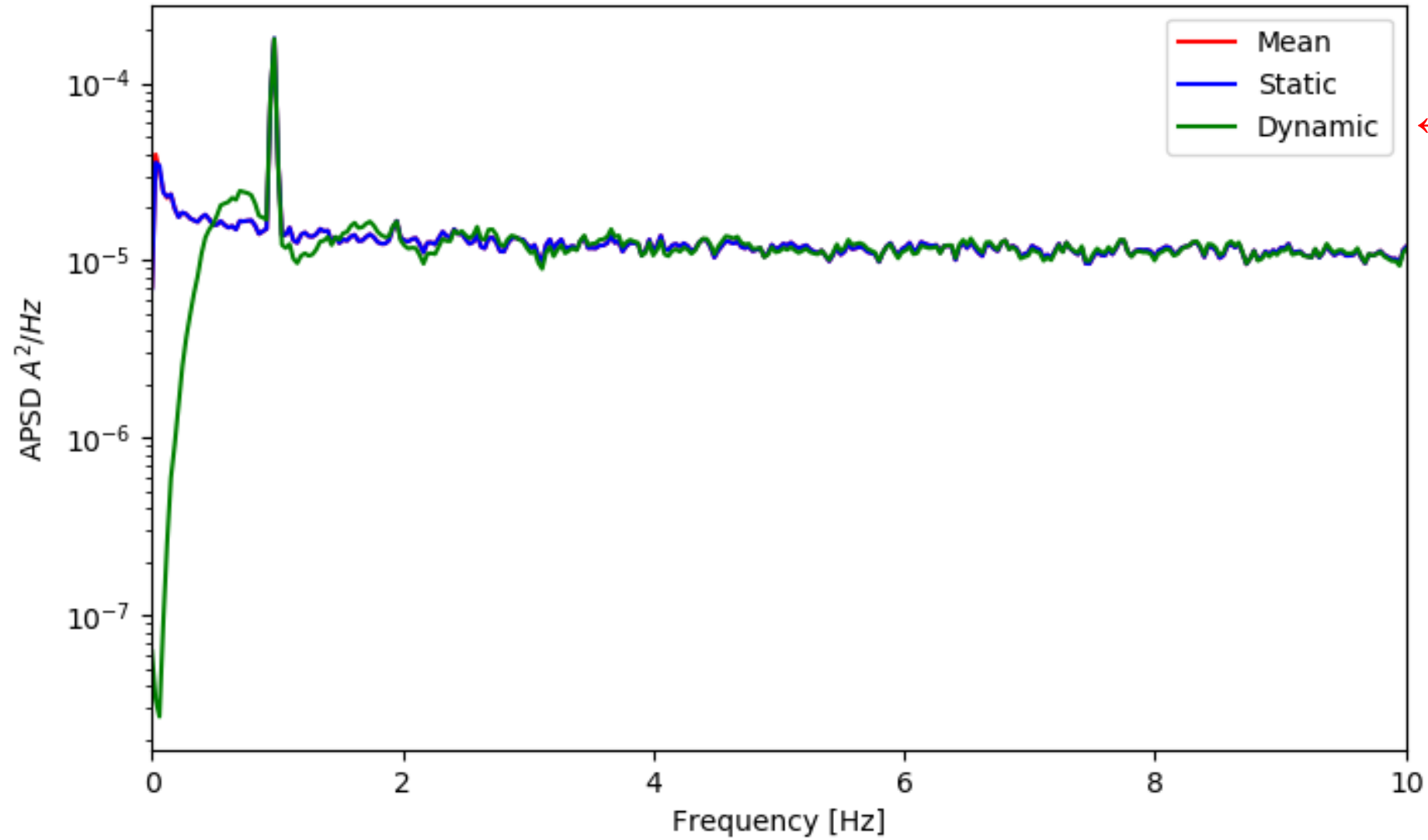
$$\Delta f = \frac{1}{\Delta t \cdot W}$$

With Δt the sampling time or dwell time

- Unwanted noise is averaged out
- Smart window selection: *removing noise **and** keeping the peak!*



Comparison of Data detrending on APSDs



← *Our selection*

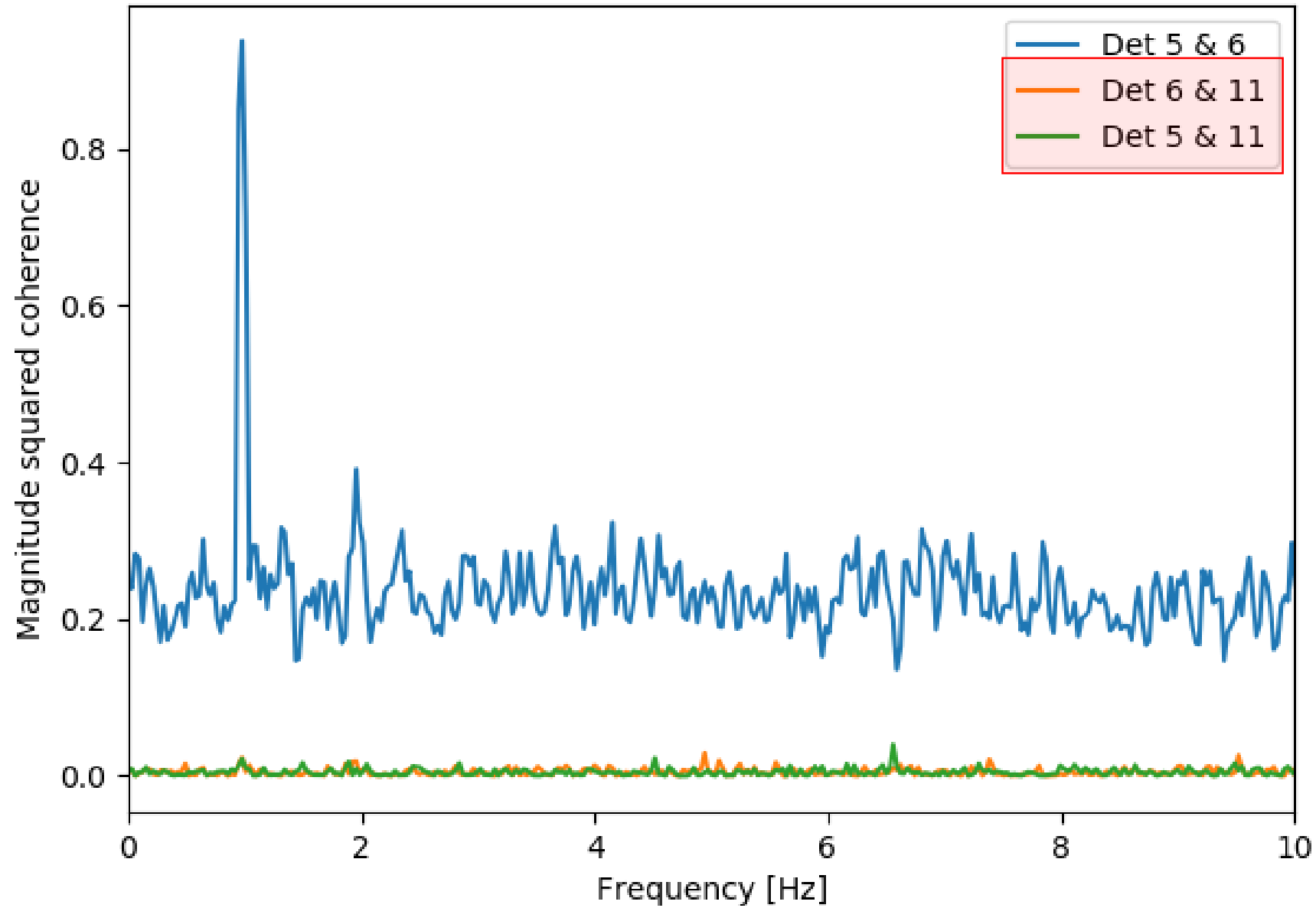
Coherence determination

- Measure of relation between two signals.
- Calculated by $C_{i,j}(f) = \frac{|CPSD_{i,j}(f)|^2}{APSD_i(f) \cdot APSD_j(f)}$
- Valued at $C_{i,j}(f) = [0,1]$
 - Higher the coherence, the more can signal i be predicted from signal j and vice-versa.
 - If $C_{i,j}(f) \sim 0$ at non-induced frequency: uncorrelated noise.
 - If $C_{i,j}(f) \sim 0$ at the induced frequency: biased data.

Even with a coherence issue, the CPSD can have a peak at the induced frequency!

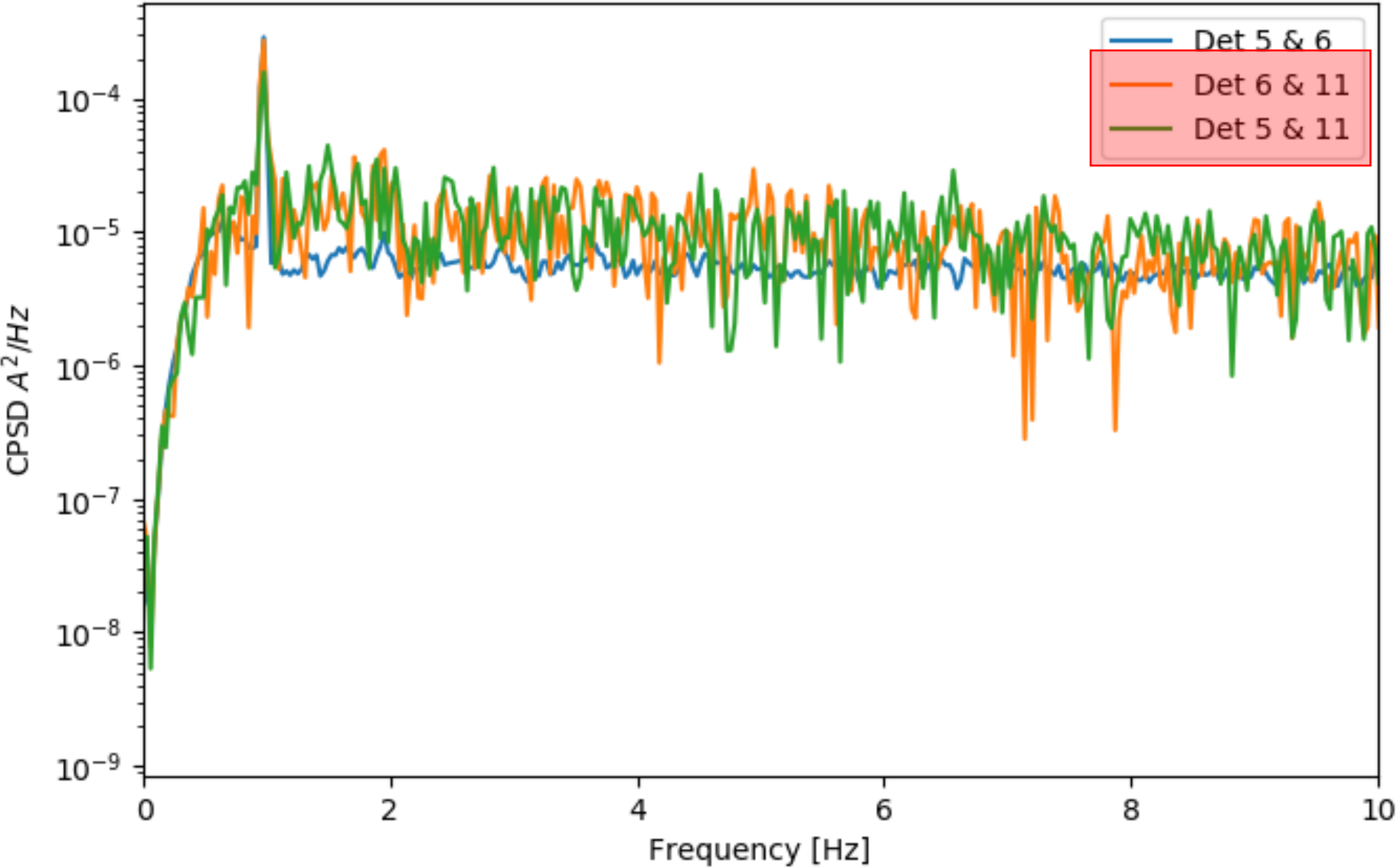


Coherence between different detectors



To be discarded...

Cross spectral density between different detectors



...although they still present a peak



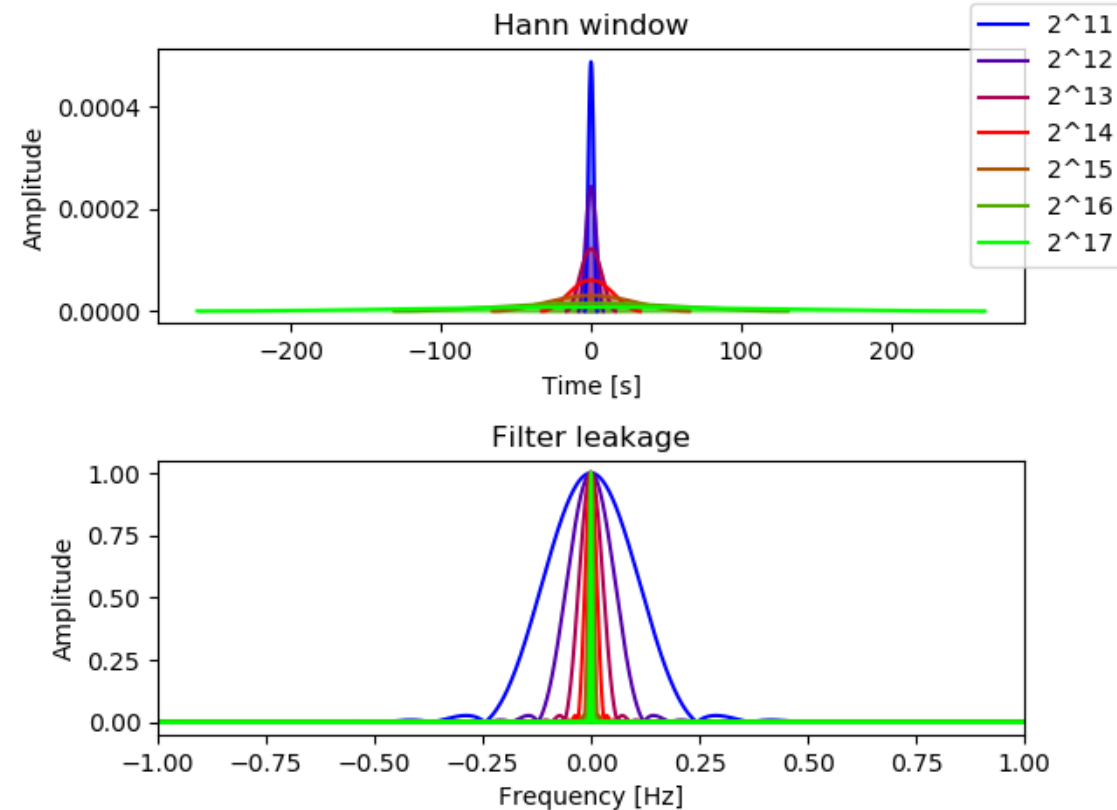
Effect of the CPSD window size

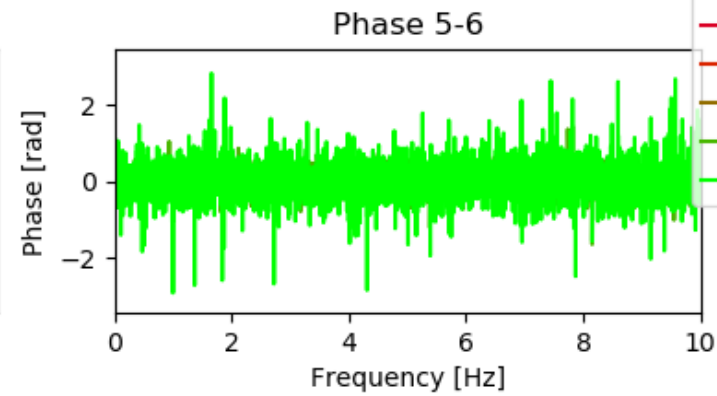
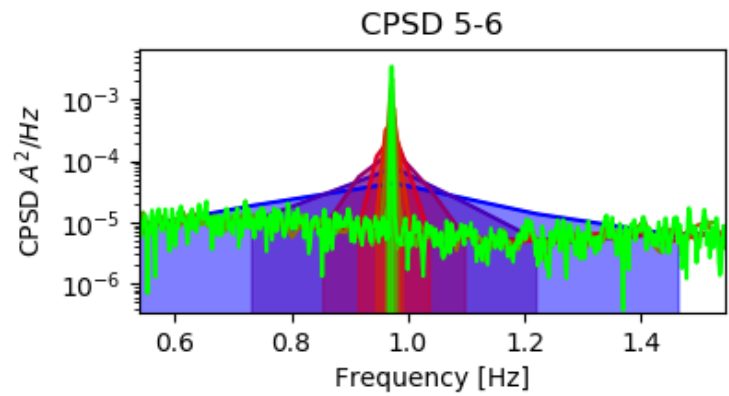
- Frequency resolution:

$$\Delta f_{min} = \frac{1}{\Delta t * W}$$

with:

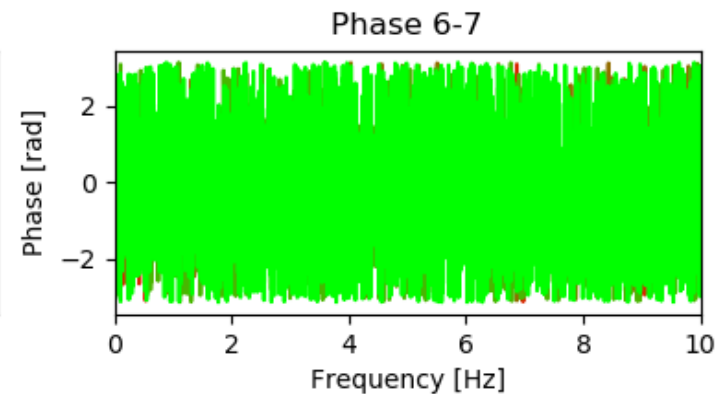
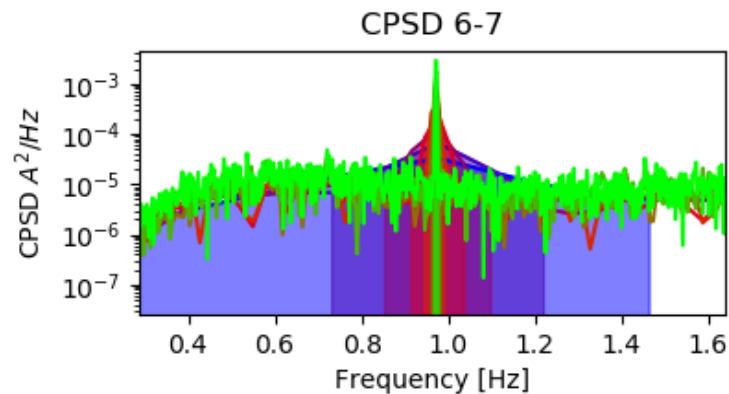
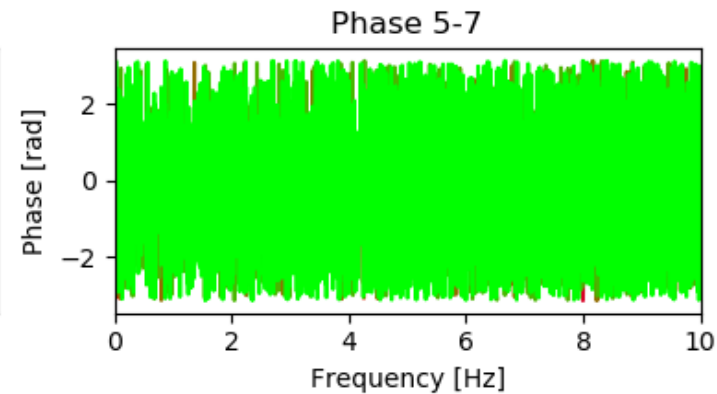
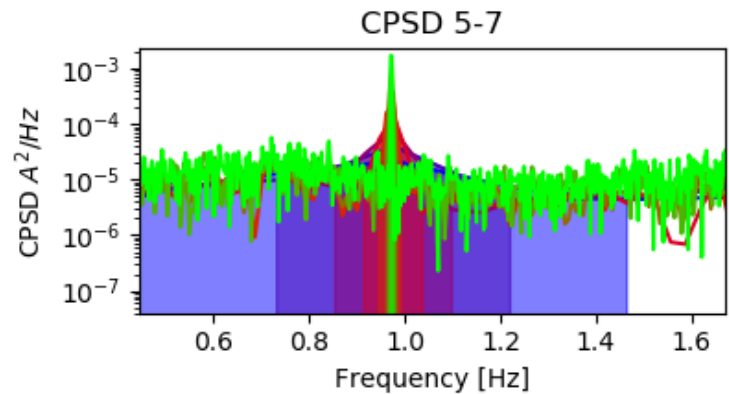
- $\Delta t = 4$ ms in our case
- W to be adapted
- Trade-off between bias elimination and spectral resolution.
 - Large W : no averaging, no noise elimination, coming back to periodogram
 - Small W : *how much of the neighbouring PSD is considered to be in peak area using a smaller window (illustrated in the exercises)?*
- Angle dependence: **not observed at all**
 - Phase shifts vs. Time → timeseries analysis will be performed in the future





- 2^{10}
- 2^{11}
- 2^{12}
- 2^{13}
- 2^{14}
- 2^{15}
- 2^{16}
- 2^{17}

← *Our selection*



- Window length is $\sim 30s$:
- i.e. ~ 30 cycles
 - 30 min: ~ 60 samples

For the PSD

- Enough samples for noise averaging
- Not too many samples for peak area estimate

For bootstrapping

- enough samples for statistical significance

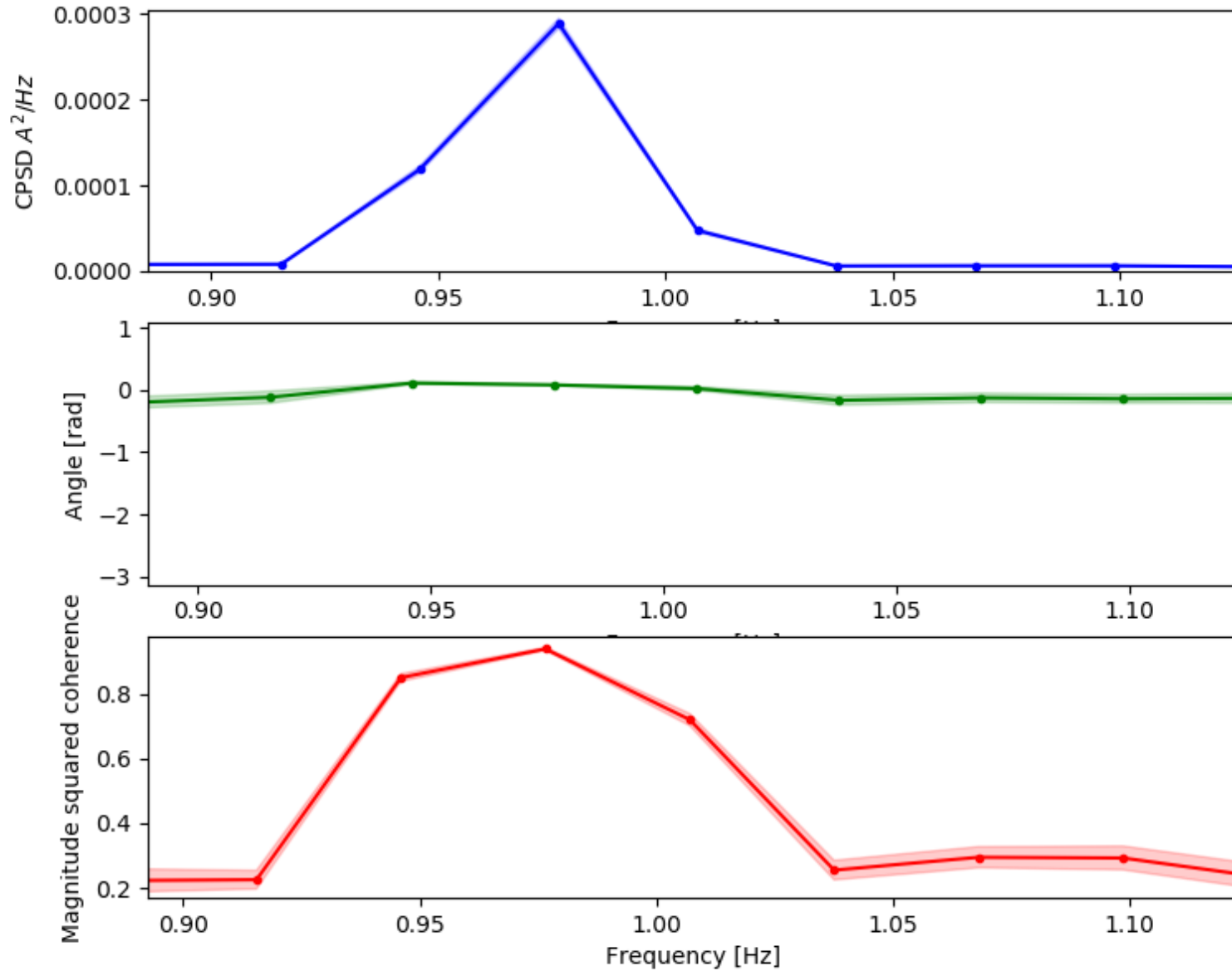
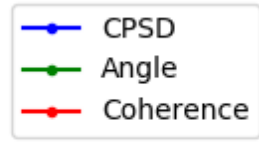


Bootstrapping

- One could directly use the standard deviation of the PSD estimate, but:
 - Problem of statistical significance
 - Forcing sensitivity to local variations and biases, i.e. hidden temporal correlations
- Bootstrapping:
 - Principle:
 - signal is chopped into (in our case equal) sections, which are resampled with replacement allowing random repetitions, for the same final length
 - timeseries are sampled multiple times using this method
 - values of interest are estimated for each combination.
 - If n sections, n^n possible combinations
- Currently:
 - Both signals are resampled in the same way, otherwise coherence is lost
 - Future developments: sections of size of peak frequency \pm frequency spread will be used for bootstrapping to observe coherence uncertainty.



Bootstrap values Det 5 & 6, window size 2^{13}



Significant spread not observed using 100 bootstrap samples.

Deviations:
-Check for distributions

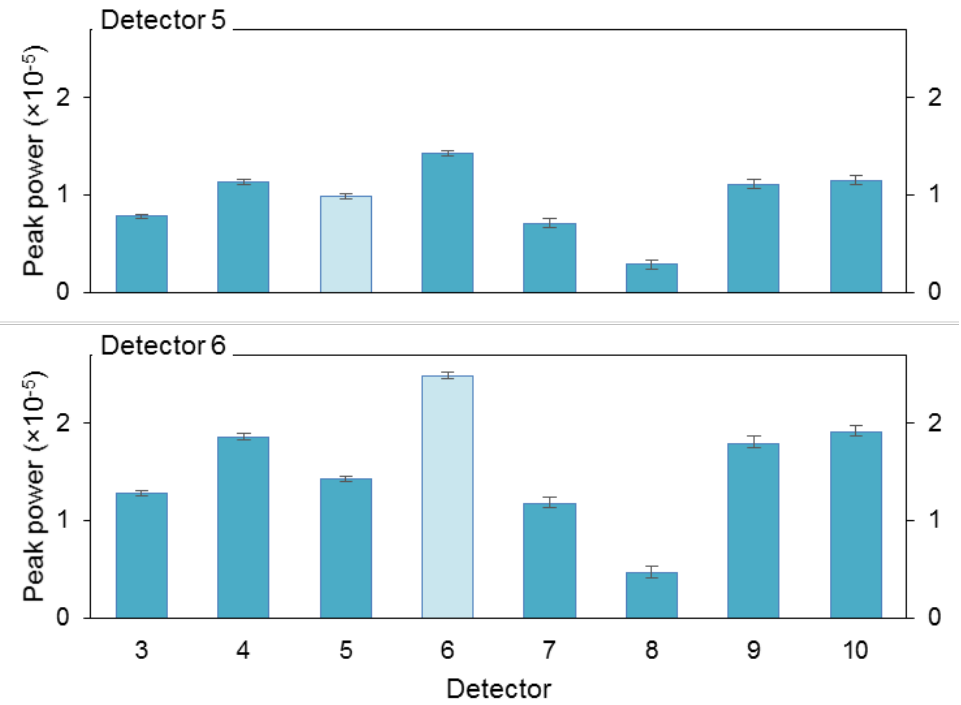


Uncertainty quantification

- One could directly use the standard deviation of the PSD estimate, but:
 - Not enough sections for statistical significance
 - Forcing sensitivity to local variations and biases, i.e. hidden temporal correlations
- Bootstrapping:
 - Principle:
 - signal is chopped into (in our case equal) sections, which are reordered with random repetitions for the same final length
 - timeseries are sampled multiple times using this method
 - values of interest are estimated for each combination.
 - If n sections, $n!$ possible combinations
- Currently:
 - Both signals are reordered in the same way, otherwise coherence is lost
 - Future developments: sections of size of peak frequency \pm frequency spread will be used for bootstrapping to observe coherence uncertainty.



Using power ratios



Using power ratios

- We define the following ratio:

$$R_{ij5}(A, f) = \frac{P_{i-j}}{P_{5-j}}$$

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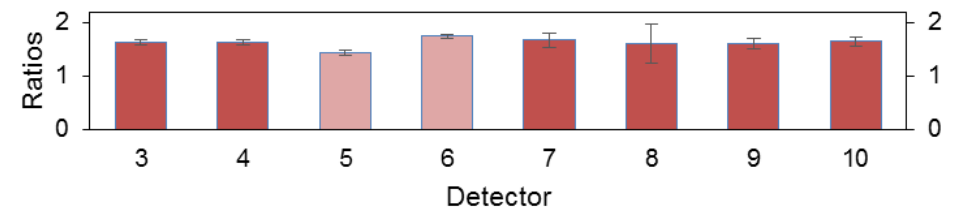
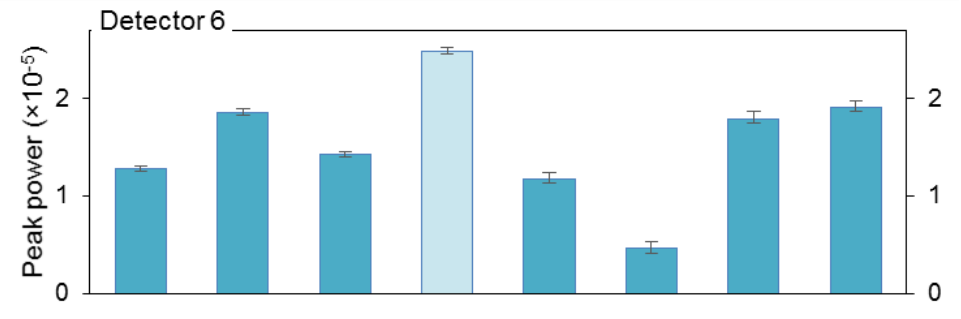
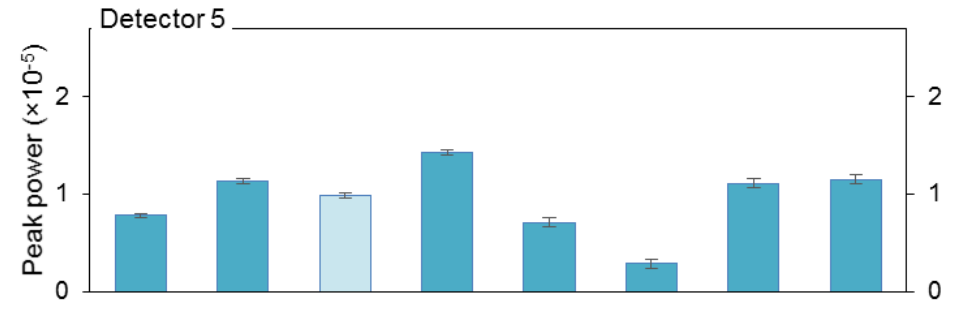
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Using power ratios

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$$R_{ij5}(A, f) = \frac{P_{i-j}}{P_{5-j}}$$

Here $R_{ij5}(A, f) = \frac{P_{6-j}}{P_{5-j}}$



Using power ratios

- For one full experiment



Detector j	Power P_{ij}								Ratios R_{ij5}								
	Detector i								Detector i								
	3	4	5	6	7	8	9	10	3	4	5	6	7	8	9	10	
3	7.11E-06	1.01E-05	7.80E-06	1.28E-05	6.22E-06	2.47E-06	9.83E-06	1.03E-05	0.911	1.30	1	1.64	0.797	0.317	1.26	1.32	
4	1.01E-05	1.51E-05	1.14E-05	1.86E-05	9.15E-06	3.77E-06	1.43E-05	1.51E-05	0.890	1.33	1	1.63	0.804	0.331	1.25	1.32	
5	7.80E-06	1.14E-05	9.90E-06	1.43E-05	7.11E-06	2.85E-06	1.11E-05	1.15E-05	0.789	1.15	1	1.44	0.718	0.288	1.12	1.16	
6	1.28E-05	1.86E-05	1.43E-05	2.49E-05	1.17E-05	4.64E-06	1.79E-05	1.91E-05	0.896	1.30	1	1.74	0.820	0.325	1.26	1.34	
7	6.22E-06	9.15E-06	7.11E-06	1.17E-05	2.57E-05	1.40E-05	8.42E-06	8.98E-06	0.874	1.29	1	1.65	3.61	1.96	1.18	1.26	
8	2.47E-06	3.77E-06	2.85E-06	4.64E-06	1.40E-05	0.00E+00	4.33E-06	4.10E-06	0.866	1.32	1	1.62	4.89	0	1.52	1.44	
9	9.83E-06	1.43E-05	1.11E-05	1.79E-05	8.42E-06	4.33E-06	3.38E-05	1.45E-05	0.883	1.28	1	1.61	0.756	0.389	3.03	1.30	
10	1.03E-05	1.51E-05	1.15E-05	1.91E-05	8.98E-06	4.10E-06	1.45E-05	3.36E-05	0.894	1.31	1	1.66	0.781	0.357	1.26	2.92	
									Ratios R_{i5}	0.896	1.31	1	1.64	0.797	0.339	1.25	1.32
									Difference with 5	-10%	31%	0%	64%	-20%	-66%	25%	32%
									Uncertainty	1.5%	1.6%	-	1.8%	3.2%	7.1%	2.5%	2.3%
									$\langle P_{i-5} \rangle$	$7.82 \cdot 10^{-6}$	$1.14 \cdot 10^{-5}$	$8.72 \cdot 10^{-6}$	$1.43 \cdot 10^{-5}$	$6.95 \cdot 10^{-6}$	$2.95 \cdot 10^{-6}$	$1.09 \cdot 10^{-5}$	$1.15 \cdot 10^{-5}$



Using power ratios

- Identification of **biases**
- Multiple estimates allows computing a standard deviation
- Reducing uncertainties

Detector j	Ratios R_{ij5}							
	Detector i							
	3	4	5	6	7	8	9	10
3	0.911	1.30	1	1.64	0.797	0.317	1.26	1.32
4	0.890	1.33	1	1.63	0.804	0.331	1.25	1.32
5	0.789	1.15	1	1.44	0.718	0.288	1.12	1.16
6	0.896	1.30	1	1.74	0.820	0.325	1.26	1.34
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Conclusion

- General outline of all steps for estimating power, phase, and associated uncertainties
- Currently developing more advanced methods, e.g.:
 - True estimate of peak area and corresponding uncertainty
 - Comparing to alternative methods, such as using autocorrelation and time-domain analysis
 - Preparation of phase analysis, using data of campaign #2 in CROCUS



Thank you!
Any question?

